

Motion Control Systems

76 mNm

V3.0, 4-Quadrant PWM with RS232 or CANopen interface

32 W

MCS 3242 ... BX4 RS/CO

Malara at 220C and manipul scales as	Mcc	2426	024BV4 BC/CO	
Values at 22°C and nominal voltage	MCS 3	242G	024BX4 RS/CO	1156
Power supply electronic	UP		12 50	V DC
Power supply motor	U_{mot}		0 50	V DC
Nominal voltage for motor	U_N		24	V
No-load speed (at Un)	no		4 900	min ⁻¹
Peak torque (S2 operation for max. 14s)	$M_{max.}$		150	mNm
Torque constant	k м		41,4	mNm/A
PWM switching frequency	f _{РWM}		100	kHz
Efficiency electronic	η		95	%
Standby current for electronic (@ $U_P=24V$)	l el		0,06	Α
Speed range (up to 30V)			1 6 200	min ⁻¹
Shaft bearings		ball bearings, preloaded		
Shaft load max.:		- '		
- with shaft diameter		5		mm
- radial at 3 000 min ⁻¹ (5 mm from mounting	flange)	50		N
- axial at 3 000 min ⁻¹ (push / pull)		5		N
- axial at standstill (push / pull)		50		N
Shaft play:				
– radial		≤ 0,015		mm
– axial		= 0		mm
Operating temperature range		-40 +100		°C
Housing material		aluminium, stainless steel		
Protection class, with option V ring		IP54		
Mass		340		g
				3

Rated values for continuous operation					
Rated torque	Mν	76	mNm		
Rated current (thermal limit)	In	1,82	Α		
Rated speed	nn	2 800	min ⁻¹		

Interface / range of functions	RS	CO	
Configuration from Motion Manager 6.0	RS232	CANopen	
Fieldbus	RS232	CANopen	
		•	
Operating modes	PP, PV, PT, CSP, CSV, CST and homing acc. to IEC 61800-7-201 or IEC 61800-7-301 as well		
	as position-, speed- and torque control via analog setpoint or voltage controller		
Speed range	see motor diagram		
Application programs	Max. 8 application programs (BASIC), one of which is an autostart function		
Additional functions	Touch-probe input, connection of a second incremental encoder, control of a holding		
	brake		
Indicator	LEDs for displaying the operating state		
	Trace as recorder (scope	e function) or logger	
	·		

Note:

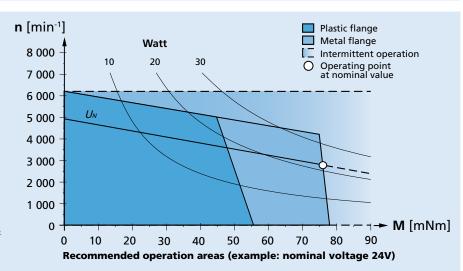
The display shows the range of possible operation points of the drives at a given ambient temperature of 22°C.

The diagram indicates the recommended speed in relation to the available torque at the output shaft.

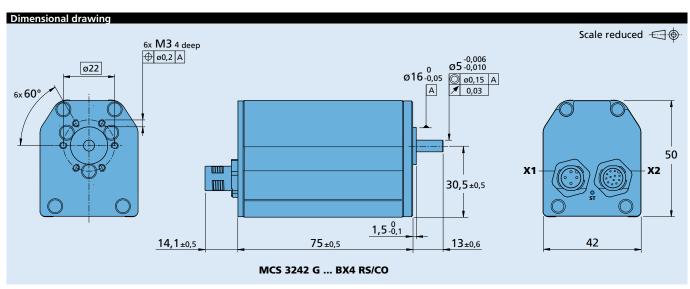
It includes the assembly on a plastic- as well as on a metal flange (assembly method: IM B 5).

The nominal voltage linear slope describes the maximal achievable operating points at nominal voltage.

Any points of operation above this linear slope will require a supply voltage $U_{mot} > U_{N.}$







Option, cable and connection information						
Example product designation: MCS3242G024BX4RS-5453						
Option	Туре	Description	Cor	nnection		
5451	Cable outlet	Radial via bottom plate	Nam	e Function	Inputs-outputs	Description
5452	Shaft seal	For use with oil emulsive substances	X1	X1 Motor and electronic		
5453	Shaft seal	IP54 according to IEC 60529		power supply		
5657	Motor flange seal	IP54 according to IEC 60529				
			X2	Inputs / outputs	Digln1, Digln2, Digln3 DigOut1, DigOut2 Anln1, Anln2 Uout / GND	TTL or. PLC level max. 0,7A continuous current ± 10V against AGND 5V
				• • • • • • • • • • • • • • • • • • •		ing manual for the NACS
			NO	te: For details on the con	nection assignment, see dev	ice manual for the MCS.

Product combination			
Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
32GPT 32/3R 42GPT 32L TL 32L ML 32L SB 32L PB		Integrated	To view our large range of accessory parts, please refer to the "Accessories" chapter.