

Motion Controllers

V2.5, 4-Quadrant PWM
with RS232 or CAN interface

MCLM 3006 S

| Values at 22°C | | MCLM 3006 S | |
|--|--------------|--------------------|------|
| Power supply electronic | U_B/U_{EL} | 12 ... 30 | V DC |
| Power supply motor ¹⁾ | $-/U_B$ | 0 ... 30 | V DC |
| PWM switching frequency | f_{PWM} | 78,12 | kHz |
| Efficiency electronic | η | 95 | % |
| Max. continuous output current | I_{cont} | 6 | A |
| Max. peak output current ²⁾ | I_{max} | 10 | A |
| Standby current for electronic (at $U_B=24V$) | I_{el} | 0,06 | A |
| Operating temperature range | | -40 ... +85 | °C |
| Housing material | | zinc, black coated | |
| Mass | | 160 | g |

¹⁾ Only available for option 3085 (separate power supply)

²⁾ S2 mode for max. 9s

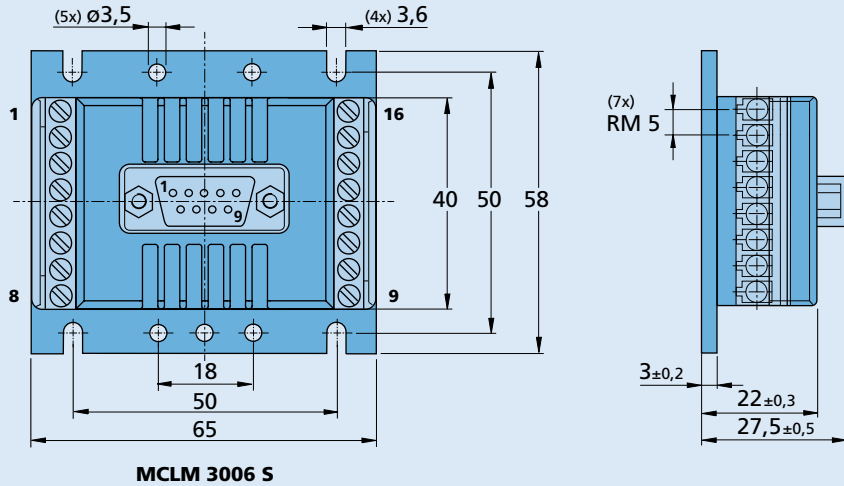

| Interfaces | MCLM 3006 S RS | MCLM 3006 S CO |
|------------|-------------------|----------------|
| Interface | RS232 | CAN (CiA) |
| Protocol | FAULHABER - ASCII | CANopen |

Basic features

- Operation of brushless linear DC-Servomotors
- Supported sensor systems: analog Hall sensors
- Positioning resolution when using analog Hall sensors as position encoder: 3000 increments per revolution
- Max. 3 digital inputs, max. 1 digital output, 1 analog input. Not all I/Os available depending on wiring
- Setpoint specification via fieldbus, quadrature signal, pulse and direction or analog inputs
- Optional stand-alone operation via application programs with the RS232 interface version

Range of functions

| | |
|-------------------------------|--|
| Operating modes (RS Versions) | Position, speed and torque control with setpoint specification via interface or analog. Position control with Gearing Mode or stepper motor operation. Operation as Servo Amplifier in voltage controller mode |
| Operating modes (CO Version) | Profile Position Mode (PP), Profile Velocity Mode (PV), Homing Mode. |
| Velocity range | 2 mm/s ... 10 000 mm/s |
| Application programs | Available in versions with RS232 interface |
| Additional functions | Overload protection for electronics and motor, self-protection from overheating, over-voltage protection in generator mode. |
| Indicator | Trace as logger |
| Motor types | Brushless Linear DC-Servomotors with analog Hall sensors |

Dimensional drawing

 Scale reduced 
Options and connection information

 Example product designation: **MCLM 3006 S RS 3085**

| Option | Type | Description | Connection | |
|--------|--------|---|--|---------------------|
| 3085 | Supply | Separate power supply for motor and electronics | No. Function | No. Function |
| | | | 1 TxD / CAN_H | 9 Sensor A |
| | | | 2 RxD / CAN_L | 10 Sensor B |
| | | | 3 AGND | 11 Sensor C |
| | | | 4 Fault | 12 U _{cc} |
| | | | 5 AnIn | 13 SGND |
| | | | 6 U _b | 14 Motor A |
| | | | 7 GND | 15 Motor B |
| | | | 8 3. In | 16 Motor C |
| | | | D-SUB connector | |
| | | | RS-232 | |
| | | | No. Function | CAN |
| | | | 2 RxD | 2 CAN_L |
| | | | 3 TxD | 3 GND |
| | | | 5 GND | 5 - |
| | | | 7 - | 7 CAN_H |
| | | | Note: For details on the connection assignment, see device manual MC. | |

Product combination
Linear DC-Servomotors

 LM 1247 ... 11
 LM 1483 ... 11
 LM 2070 ... 11

Cables / Accessories

To view our large range of accessory parts, please refer to the „Accessories“ chapter.