

# Motion Controllers

V2.5, 4-Quadrant PWM  
with RS232 or CAN interface

## MCBL 3006 S

Values at 22°C		MCBL 3006 S	
Power supply electronic	$U_B/U_{EL}$	12 ... 30	V DC
Power supply motor <sup>1)</sup>	$-U_B$	0 ... 30	V DC
PWM switching frequency	$f_{PWM}$	78,12	kHz
Efficiency electronic	$\eta$	95	%
Max. continuous output current	$I_{cont}$	6	A
Max. peak output current <sup>2)</sup>	$I_{max}$	10	A
Standby current for electronic (at $U_B=24V$ )	$I_{el}$	0,06	A
Operating temperature range		-40 ... +85	°C
Housing material		zinc, black coated	
Mass		160	g

<sup>1)</sup> Only available for option 3085 (separate power supply)

<sup>2)</sup> S2 mode for max. 9s

Interfaces	MCBL 3006 S RS	MCBL 3006 S CF	MCBL 3006 S CO
Interface	RS232	CAN (FAULHABER channel)	CAN (CiA)
Protocol	FAULHABER - ASCII	CANopen	CANopen

### Basic features

- Supported sensor systems: analog Hall sensors
- Positioning resolution when using analog Hall sensors as position encoder: 3000 increments per revolution
- Max. 3 digital inputs, max. 1 digital output, 1 analog input. Not all I/Os available depending on wiring
- Setpoint specification via fieldbus, quadrature signal, pulse and direction or analog inputs
- Optional stand-alone operation via application programs with the RS232 interface version

### Range of functions

Operating modes (RS and CF Versions)	Position, speed and torque control with setpoint specification via interface or analog. Position control with Gearing Mode or stepper motor operation. Operation as Servo Amplifier in voltage controller mode
Operating modes (CF and CO Versions)	Profile Position Mode (PP), Profile Velocity Mode (PV), Homing Mode.
Speed range for brushless motors with number of pole pairs 1	5 min <sup>-1</sup> ... 30 000 min <sup>-1</sup> (with sinus commutation)
Application programs	Available in versions with RS232 interface
Additional functions	Overload protection for electronics and motor, self-protection from overheating, over-voltage protection in generator mode.
Indicator	Trace as logger
Motor types	Brushless DC-motors with analog Hall sensors and number of pole pairs 1 or 2

