

Accessories

Programming Adapter CxD for Motion Control Systems V2.5 RS232/CAN interface

1) The pin assignments of X3 depend on the position of switches 3 and 4 of DIP switch S1.

Part No.: 6501.00113

6501.00113	
– 10 + 65	°C
60 x 50 x 15	mm
30	g
	- 10 + 65 60 x 50 x 15

Note: All switches are in the "OFF" position in the as-delivered condition. These switches must be set accordingly depending on the application.

General information The programming adapter is used to connect Brushless DC-Servomotors with Pin assignment integrated Motion Controller and a serial RS232 or CAN interface. Pin Connection X1 Pin Connection X2 1 3. ln The different operating modes can be selected using the 6 DIP switches. 1 3. In 2 +24V 2 +24V A Brushless DC-Servomotor with integrated Motion Controller can be connected 3 GND 3 GND to each programming adapter. 4 An In 4 An In 5 AGND 5 AGND Description of DIP switch (S1) settings 6 Fault 6 Fault 1: Fault Pull-up resistor with LED connected to programming adapter. 7 RS-232 RxD / CAN-L 7 RS-232 RxD / CAN-I Open collector 8 RS-232 TxD / CAN-H 8 RS-232 TxD / CAN-H 9 n.c. 120Ω terminating resistor for the final node in the 2: Term ON 10 n.c. CAN network connected to the programming adapter. Terminating resistor not connected at RS232 operation 1) at CAN operation 1) Pin Connection X3 Pin Connection X3 3: CAN 1) ON Operation with CAN interface RS-232 / RxD 2 CAN L OFF . Deactivated 3 RS-232 / TxD 3 GND 4: RS232 1) Operation with RS232 interface 5 GND ON 7 CAN H OFF Deactivated 5: NETMODE ON Pull-down resistor (2,2 k Ω) for RS232 wiring connected. This may only be connected to a node in the RS232 network. Pin Connection X4 LED Status OFF Deactivated +24V LED illuminates GND 6: AGND AGND and GND interconnected. ON no error fault output switched 3 An In AGND and GND disconnected (with separate ground). 4 AGND to GND 5 Fault LED does not illuminate 6 3. In error fault output

