

**PRELIMINARY**

**Brushless Flat DC-Servomotors**  
External rotor technology, with housing

**112 mNm**  
**60 W**

**Series 4221 ... BXT H**

Values at 22°C and nominal voltage		4221 G	018 BXT H	024 BXT H	048 BXT H	
1	Nominal voltage	$U_N$	18	24	48	V
2	Terminal resistance, phase-phase	$R$	0,46	0,74	2,6	$\Omega$
3	Efficiency, max.	$\eta_{max}$	88	87	88	%
4	No-load speed	$n_0$	5 710	6 040	6 070	min <sup>-1</sup>
5	No-load current, typ. (with shaft $\varnothing$ 5 mm)	$I_0$	0,177	0,139	0,103	A
6	Starting torque	$M_A$	1 170	1 220	1 390	mNm
7	Speed constant	$k_n$	320	253	127	min <sup>-1</sup> /V
8	Back-EMF constant	$k_E$	3,13	3,95	7,87	mV/min <sup>-1</sup>
9	Slope of n-M curve	$\Delta n/\Delta M$	4,93	4,97	4,4	min <sup>-1</sup> /mNm
10	Terminal inductance, phase-phase	$L$	396	664	2 550	$\mu$ H
11	Mechanical time constant	$\tau_m$	3,56	3,59	3,18	ms
12	Rotor inertia	$J$	69	69	69	gcm <sup>2</sup>
13	Angular acceleration	$\alpha_{max}$	169	177	201	$\cdot 10^3$ rad/s <sup>2</sup>
14	Operating temperature range:					
	– motor		-40 ... +100			°C
	– winding, max. permissible		+125			°C
15	Shaft bearings		ball bearings, preloaded			
16	Shaft load max.:					
	– with shaft diameter		5			mm
	– radial at 3 000 min <sup>-1</sup> (5 mm from mounting flange)		25			N
	– axial at 3 000 min <sup>-1</sup> (push / pull)		4			N
	– axial at standstill (push / pull)		50			N
17	Shaft play:					
	– radial	$\leq$	0,015			mm
	– axial	$=$	0			mm
18	Mass		142			g
19	Direction of rotation		electronically reversible			
20	Speed up to	$n_{max}$	10 000			min <sup>-1</sup>
21	Number of pole pairs		7			
22	Hall sensors		digital			
23	Magnet material		NdFeB			

Rated values for continuous operation						
24	Rated torque	$M_N$	102	112	107	mNm
25	Rated current (thermal limit)	$I_N$	3,33	2,87	1,39	A
26	Rated speed	$n_N$	3 980	4 380	4 700	min <sup>-1</sup>
27	Rated slope of n-M curve	$\Delta n/\Delta M$	17	14,8	12,8	min <sup>-1</sup> /mNm

**Note:** Rated values are measured at nominal voltage and 22°C ambient temperature.

**Note:**

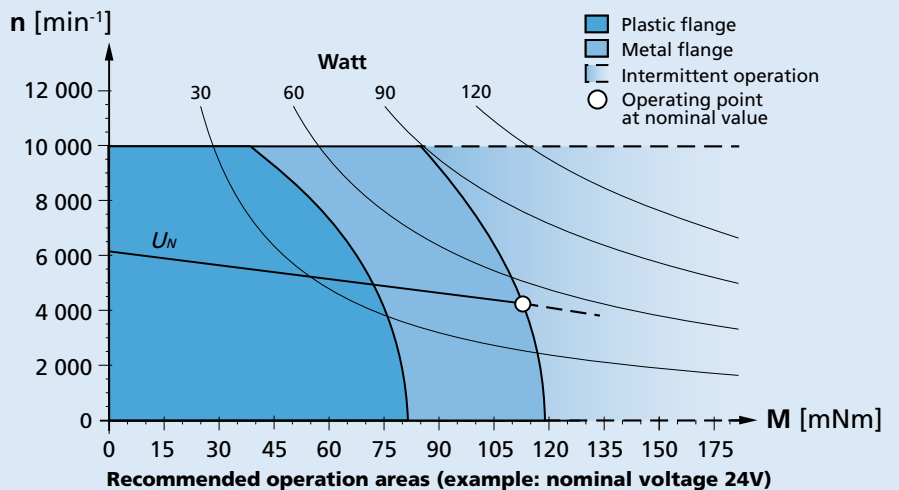
The display shows the range of possible operation points of the drives at a given ambient temperature of 22°C.

The diagram indicates the recommended speed in relation to the available torque at the output shaft.

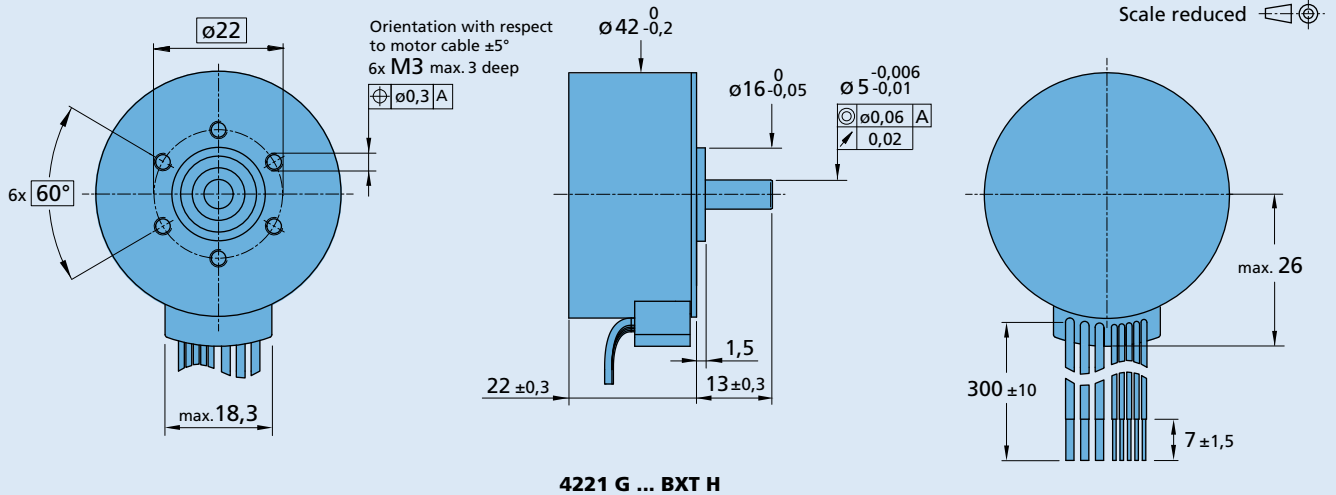
It includes the assembly on a plastic- as well as on a metal flange (assembly method: IM B 5).

The nominal voltage linear slope describes the maximal achievable operating points at nominal voltage.

Any points of operation above this linear slope will require a supply voltage  $U_{mot} > U_N$ .



### Dimensional drawing



### Option, cable and connection information

Example product designation: **4221G018BXTH-3830**

Option	Type	Description	Connection	
			Function	Colour
3830		Standard cable with connector MOLEX Microfit 3.0, 43025-0800, recommended mating connector 43020-0800	Phase C	yellow
			Phase B	orange
			Phase A	brown
			GND	black
			U <sub>DD</sub> (+5V)	red
			Hall sensor C	grey
			Hall sensor B	blue
			Hall sensor A	green
			<b>Standard cable</b>	
			Single wires, material PVC, AWG 20, Phase A/B/C	
			AWG 26, Hall A/B/C, U <sub>DD</sub> , GND	

### Product combination

Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
32A 38/1 S 38/2 S	IE3-1024 IE3-1024 L IERS3-500 IERS3-500 L IER3-10000 IER3-10000 L	SC 2804 S SC 5004 P SC 5008 S MC 5004 P MC 5005 S	To view our large range of accessory parts, please refer to the "Accessories" chapter.