

Brushless DC-Servomotors

4 Pole Technology

96 mNm
62 W

Series 3268 ... BX4

| Values at 22°C and nominal voltage | 3268 G | 018 BX4 | 024 BX4 | 030 BX4 | 036 BX4 | 042 BX4 | 048 BX4 | |
|---|-------------------------|---------------------------|---------------------|---------------------|---------------------|---------------------|---------------------|------------------------------------|
| 1 Nominal voltage | U_N | 18 | 24 | 30 | 36 | 42 | 48 | V |
| 2 Terminal resistance, phase-phase | R | 0,92 | 1,47 | 2,08 | 3,23 | 4,83 | 6,06 | Ω |
| 3 Efficiency, max. | η_{max} | 80 | 81 | 80 | 80 | 80 | 79 | % |
| 4 No-load speed | n_0 | 5 100 | 5 500 | 5 700 | 5 500 | 5 300 | 5 500 | min^{-1} |
| 5 No-load current, typ. (with shaft \varnothing 5 mm) | I_0 | 0,22 | 0,183 | 0,162 | 0,124 | 0,101 | 0,093 | A |
| 6 Stall torque | M_H | 670 | 705 | 742 | 716 | 670 | 678 | mNm |
| 7 Friction torque, static | C_0 | 1,6 | 1,6 | 1,6 | 1,6 | 1,6 | 1,6 | mNm |
| 8 Friction torque, dynamic | C_V | $1,1 \cdot 10^{-3}$ | $1,1 \cdot 10^{-3}$ | $1,1 \cdot 10^{-3}$ | $1,1 \cdot 10^{-3}$ | $1,1 \cdot 10^{-3}$ | $1,1 \cdot 10^{-3}$ | $\text{mNm}/\text{min}^{-1}$ |
| 9 Speed constant | k_n | 278 | 220 | 185 | 148 | 124 | 111 | min^{-1}/V |
| 10 Back-EMF constant | k_E | 3,595 | 4,534 | 5,392 | 6,741 | 8,088 | 8,987 | $\text{mV}/\text{min}^{-1}$ |
| 11 Torque constant | k_M | 34,3 | 43,5 | 51,5 | 64,4 | 77,2 | 85,8 | mNm/A |
| 12 Current constant | k_I | 0,029 | 0,023 | 0,019 | 0,015 | 0,013 | 0,012 | A/mNm |
| 13 Slope of n-M curve | $\Delta n/\Delta M$ | 7,45 | 7,5 | 7,48 | 7,44 | 7,73 | 7,85 | $\text{min}^{-1}/\text{mNm}$ |
| 14 Terminal inductance, phase-phase | L | 67,6 | 110 | 152 | 238 | 342 | 423 | μH |
| 15 Mechanical time constant | τ_m | 4,9 | 4,9 | 4,9 | 4,9 | 5,1 | 5,2 | ms |
| 16 Rotor inertia | J | 63 | 63 | 63 | 63 | 63 | 63 | gcm^2 |
| 17 Angular acceleration | α_{max} | 106 | 112 | 118 | 114 | 106 | 108 | $\cdot 10^3 \text{rad}/\text{s}^2$ |
| 18 Thermal resistance | R_{th1} / R_{th2} | 1,7 / 8,8 | | | | | | K/W |
| 19 Thermal time constant | τ_{w1} / τ_{w2} | 16 / 1 080 | | | | | | s |
| 20 Operating temperature range: | | | | | | | | |
| – motor | | -40 ... +100 | | | | | | $^{\circ}\text{C}$ |
| – winding, max. permissible | | +125 | | | | | | $^{\circ}\text{C}$ |
| 21 Shaft bearings | | ball bearings, preloaded | | | | | | |
| 22 Shaft load max.: | | | | | | | | |
| – with shaft diameter | | 5 | | | | | | mm |
| – radial at 3 000 min^{-1} (5 mm from mounting flange) | | 50 | | | | | | N |
| – axial at 3 000 min^{-1} (push / pull) | | 5 | | | | | | N |
| – axial at standstill (push / pull) | | 50 | | | | | | N |
| 23 Shaft play: | | | | | | | | |
| – radial | \leq | 0,015 | | | | | | mm |
| – axial | $=$ | 0 | | | | | | mm |
| 24 Housing material | | stainless steel | | | | | | |
| 25 Mass | | 290 | | | | | | g |
| 26 Direction of rotation | | electronically reversible | | | | | | |
| 27 Speed up to | n_{max} | 12 000 | | | | | | min^{-1} |
| 28 Number of pole pairs | | 2 | | | | | | |
| 29 Hall sensors | | digital | | | | | | |
| 30 Magnet material | | NdFeB | | | | | | |
| Rated values for continuous operation | | | | | | | | |
| 31 Rated torque | M_N | 74,5 | 72 | 69,8 | 71,9 | 71,7 | 70 | mNm |
| 32 Rated current (thermal limit) | I_N | 2,63 | 2 | 1,66 | 1,36 | 1,13 | 1 | A |
| 33 Rated speed | n_N | 4 550 | 4 890 | 5 210 | 4 950 | 4 750 | 4 920 | min^{-1} |

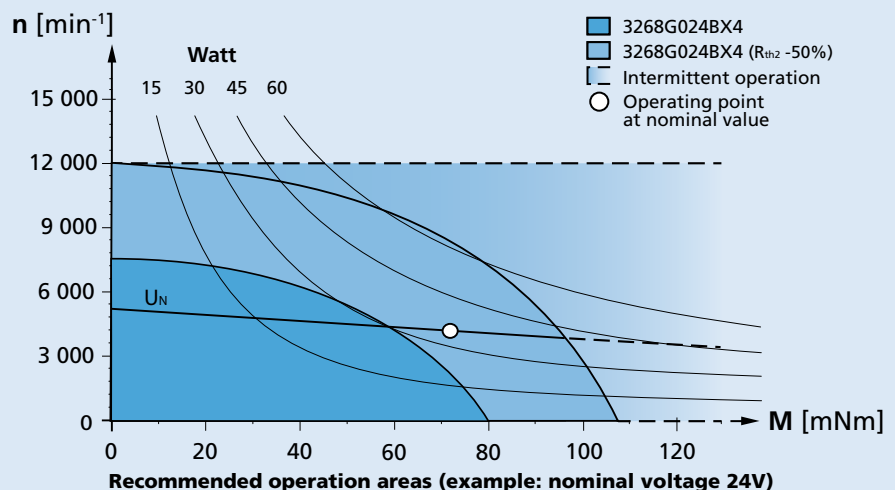
Note: Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The R_{th2} value has been reduced by 25%.

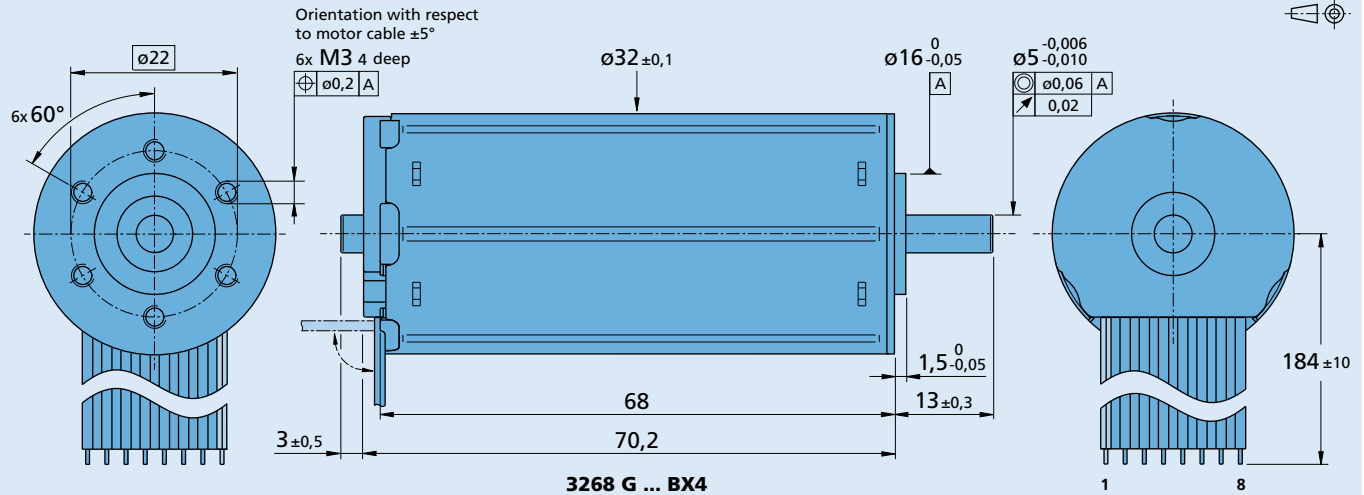
Note:

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition (R_{th2} 50% reduced).

The nominal voltage (U_N) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



Dimensional drawing

Option, cable and connection information

 Example product designation: **3268G024BX4-3692**

| Option | Type | Description | Connection standard | |
|--------|------------------------|--|---------------------|-----------------------|
| | | | No. | Function |
| 3830 | Connector | AWG 26 / PVC ribbon cable with connector MOLEX Microfit 3.0, 43025-0800, recommended mating connector 43020-0800 | 1 | Phase C |
| 4935 | Single wires | Motor with single wires (PTFE), length 184 mm, AWG22 | 2 | Phase B |
| X4935 | Single wires | Motor with single wires (PTFE), length 300 mm, AWG22 | 3 | Phase A |
| Y4935 | Single wires | Motor with single wires (PTFE), length 600 mm, AWG22 | 4 | GND |
| 4747 | Temperature range | Up to 150°C, winding max. 150°C, with single wires (PTFE), length 184 mm, AWG22 | 5 | U _{DD} (+5V) |
| X4747 | Temperature range | Up to 150°C, winding max. 150°C, with single wires (PTFE), length 300 mm, AWG22 | 6 | Hall sensor C |
| Y4747 | Temperature range | Up to 150°C, winding max. 150°C, with single wires (PTFE), length 600 mm, AWG22 | 7 | Hall sensor B |
| Y158 | Shaft end | Motor without second shaft end | 8 | Hall sensor A |
| 3692 | Controller combination | Analog Hall sensors for combination with Motion Controller MCBL | | |

| Option: 4935/4747 | | |
|-----------------------|-----------------------|--------|
| Function | Function | Colour |
| Phase C | Phase C | yellow |
| Phase B | Phase B | orange |
| Phase A | Phase A | brown |
| GND | GND | black |
| U _{DD} (+5V) | U _{DD} (+5V) | red |
| Hall sensor C | Hall sensor C | grey |
| Hall sensor B | Hall sensor B | blue |
| Hall sensor A | Hall sensor A | green |

| Standard cable | |
|-----------------------------|--|
| Insulation: PVC | |
| 8 conductors, AWG 24 | |
| pitch 2,54 mm, wires tinned | |

Product combination

| Precision Gearheads / Lead Screws | Encoders | Drive Electronics | Cables / Accessories |
|-----------------------------------|--------------|-------------------|---|
| 32GPT | IE3-1024 | SC 2804 S | MBZ Brake MBZ is available in combination with analog Hall sensors only. To view our large range of accessory parts, please refer to the "Accessories" chapter. |
| 32/3 | IE3-1024 L | SC 5004 P | |
| 32/3R | IER3-10000 | SC 5008 S | |
| 38/1 | IER3-10000 L | MCBL 3003 P | |
| 38/1 S | AEMT-12/16 L | MCBL 3006 S | |
| 38/2 | AES-4096 L | MC 5004 P | |
| 38/2 S | | MC 5005 S | |
| 42GPT | | MC 5010 S | |