

# DC-Micromotors

## Graphite Commutation

12 mNm  
11 W

### Series 2237 ... CXR

Values at 22°C and nominal voltage	2237 S	006 CXR	012 CXR	018 CXR	024 CXR	036 CXR	048 CXR		
1 Nominal voltage	$U_N$	6	12	18	24	36	48	V	
2 Terminal resistance	$R$	0,85	3,92	8,5	15,7	33	62,8	$\Omega$	
3 Efficiency, max.	$\eta_{max}$	68,1	70,8	72,2	72,6	73,6	73,5	%	
4 No-load speed	$n_0$	6 900	6 800	7 000	6 900	7 200	7 000	min <sup>-1</sup>	
5 No-load current, typ. (with shaft $\varnothing$ 3 mm)	$I_0$	0,124	0,058	0,039	0,029	0,02	0,015	A	
6 Stall torque	$M_H$	47,2	45,7	47,1	46,6	48,7	47,1	mNm	
7 Friction torque	$M_R$	0,92	0,92	0,92	0,92	0,92	0,92	mNm	
8 Speed constant	$k_n$	1 283	601	409	301	207	150	min <sup>-1</sup> /V	
9 Back-EMF constant	$k_E$	0,78	1,66	2,44	3,33	4,83	6,65	mV/min <sup>-1</sup>	
10 Torque constant	$k_M$	7,44	15,9	23,3	31,8	46,2	63,5	mNm/A	
11 Current constant	$k_I$	0,134	0,063	0,043	0,032	0,022	0,016	A/mNm	
12 Slope of n-M curve	$\Delta n / \Delta M$	146	148	149	149	148	149	min <sup>-1</sup> /mNm	
13 Rotor inductance	$L$	35	150	320	590	1 240	2 340	$\mu$ H	
14 Mechanical time constant	$\tau_m$	5	5	5	5	5	5	ms	
15 Rotor inertia	$J$	3,1	3,1	3,1	3,1	3,1	3,1	gcm <sup>2</sup>	
16 Angular acceleration	$\alpha_{max}$	152	147	152	150	157	152	$\cdot 10^3$ rad/s <sup>2</sup>	
17 Thermal resistance	$R_{th1} / R_{th2}$	8 / 17						K/W	
18 Thermal time constant	$\tau_{w1} / \tau_{w2}$	13 / 500						s	
19 Operating temperature range:									
– motor		-30 ... +100						°C	
– winding, max. permissible		+125						°C	
20 Shaft bearings		sintered bearings (standard)			ball bearings, preloaded (optional version)				
21 Shaft load max.:									
– with shaft diameter		3			3				mm
– radial at 3 000 min <sup>-1</sup> (3 mm from bearing)		2,5			15				N
– axial at 3 000 min <sup>-1</sup>		0,3			2				N
– axial at standstill		20			20				N
22 Shaft play:									
– radial	$\leq$	0,03			0,015				mm
– axial	$\leq$	0,15			0				mm
23 Housing material		steel, zinc galvanized and passivated							
24 Mass		68						g	
25 Direction of rotation		clockwise, viewed from the front face							
26 Speed up to	$n_{max}$	8 000						min <sup>-1</sup>	
27 Number of pole pairs		1							
28 Magnet material		NdFeB							
<b>Rated values for continuous operation</b>									
29 Rated torque	$M_N$	11	12	12	12	12	12	mNm	
30 Rated current (thermal limit)	$I_N$	1,9	0,9	0,61	0,46	0,31	0,23	A	
31 Rated speed	$n_N$	4 750	4 450	4 700	4 560	4 880	4 630	min <sup>-1</sup>	

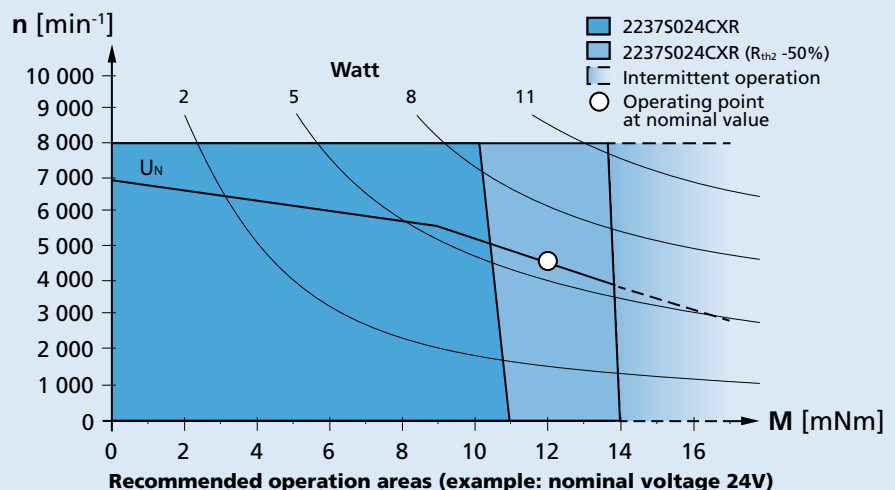
**Note:** Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The  $R_{th2}$  value has been reduced by 25%.

**Note:**

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition ( $R_{th2}$  50% reduced).

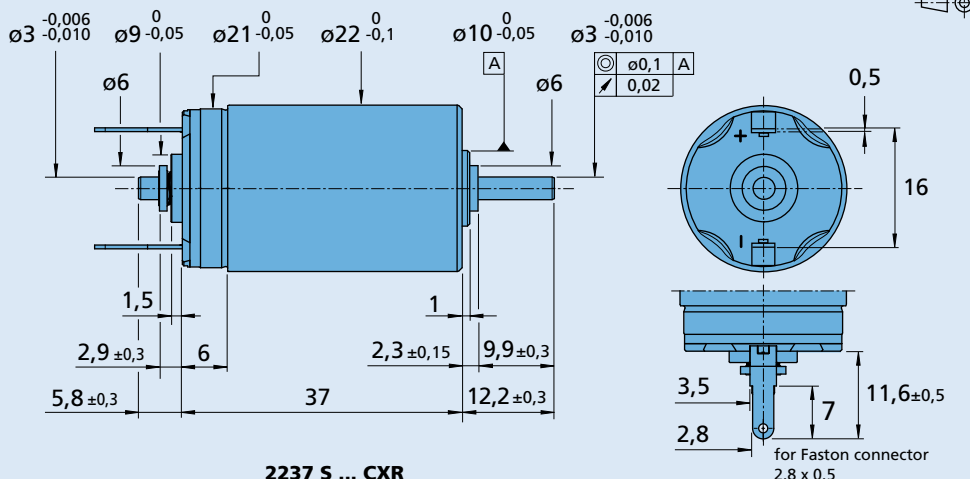
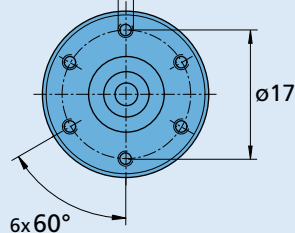
The nominal voltage ( $U_N$ ) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



### Dimensional drawing

Orientation with respect to motor terminals not defined

6x  $\oplus_{\oplus} \varnothing 0,3 \text{ A}$  M2 2,5 deep



2237 S ... CXR

### Options

Example product designation: **2237S012CXR-275**

Option	Type	Description
U	Single Leads	For motors with single leads (PTFE), length 160 mm, red (+) / black (-)
158	Shaft end	No second shaft end
275	Ball bearings	Motor with 2 preloaded ball bearings.

### Product combination

Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
22E 22EKV 22GPT 22/7 23/1 26A	IE3-1024 IE3-1024 L IERS3-500 IERS3-500 L IER3-10000 IER3-10000 L	SC 1801 P SC 1801 S SC 2402 P SC 2804 S SC 5004 P SC 5008 S MCDC 3002 P MCDC 3002 S MCDC 3003 P MCDC 3006 S MC 5004 P MC 5005 S	To view our large range of accessory parts, please refer to the "Accessories" chapter.